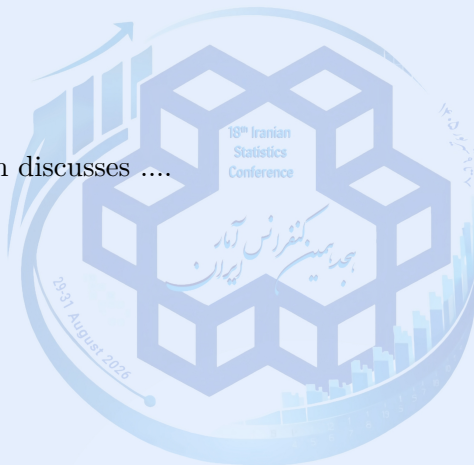




Abstract

This presentation discusses



Introduction



Notations and definitions

A sample unnumbered formula is given below:

$$\max_{x \in \mathbb{R}} f(x).$$

Here is a sample of a numbered formula:

$$G_F(x) = \frac{1}{B(\alpha, \beta)} \int_0^{F(x)} t^{\alpha-1} (1-t)^{\beta-1} dt, \quad \alpha > 0, \beta > 0. \quad (1)$$

Below is a multiline formula that is the derivative of equation (1):

$$\begin{aligned} g_F(x) &= \frac{d}{dx} G_F(x) \\ &= \frac{1}{B(\alpha, \beta)} f(x) (F(x))^{\alpha-1} (\bar{F}(x))^{\beta-1}. \end{aligned} \quad (2)$$

Figures

Below is a sample table. Table 1 contains four rows and three columns.

Table : Table title should be here.

Column One	Column Two	Column Three
1	2	3
4	5	6
7	8	9

Tables and Figures

Below is a sample figure. Figure 1 contains two subfigures.

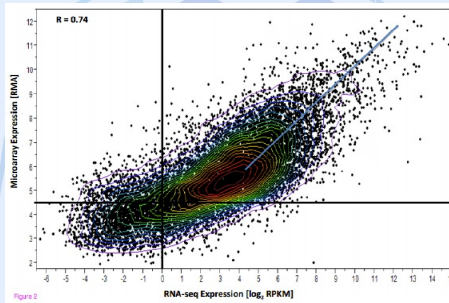


Figure : Figure caption should be placed here.

Discussion

Definition 1

This is a definition.

Theorem 1

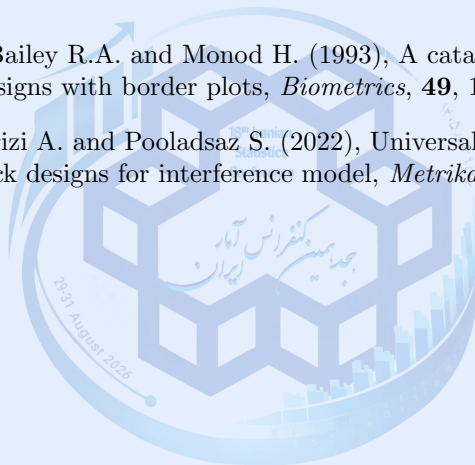
This is a Theorem.

Lemma 1

This is a Lemma.

References

- Azaïs J.M., Bailey R.A. and Monod H. (1993), A catalogue of efficient neighbour-designs with border plots, *Biometrics*, **49**, 1252–1261.
- Fakhari-Esferizi A. and Pooladsaz S. (2022), Universally optimal balanced block designs for interference model, *Metrika*, **85**, 1049–1061.



Thank you for your attention!

